

# **MAT124 MATHEMATICS II**

An Application of Multiple Integrals, Integration in Cylindrical Coordinates, Integration in Spherical Coordinates, Change of Variables in Triple Integrals

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# Outline

An Application of Multiple Integrals

Moments and Centers of Mass

Change of Variables in Triple Integrals

Integration in Cylindrical Coordinates

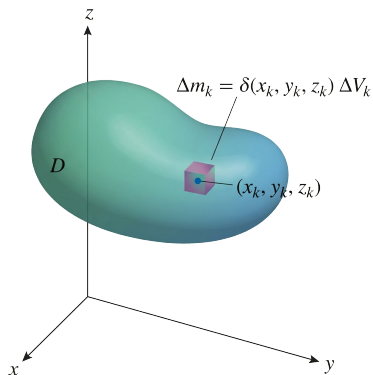
Integration in Spherical Coordinates

Substitutions in Triple Integrals

# **An Application of Multiple Integrals**

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## Masses and First Moments



If  $\delta(x, y, z)$  is the density (mass per unit volume) of an object occupying a region  $D$  in space, the integral of  $\delta$  over  $D$  gives the **mass** of the object. To see why, imagine partitioning the object into  $n$  mass elements.

The object's mass is the limit

$$\begin{aligned} M &= \lim_{n \rightarrow \infty} \sum_{k=1}^n \Delta m_k \\ &= \lim_{n \rightarrow \infty} \sum_{k=1}^n \delta(x_k, y_k, z_k) \Delta V_k \\ &= \iiint_D \delta(x, y, z) dV. \end{aligned}$$

## Masses and First Moments

The **first moment** of a solid region  $D$  about a coordinate plane is defined as the triple integral over  $D$  of the distance from a point  $(x, y, z)$  in  $D$  to the plane multiplied by the density of the solid at that point. For instance, the first moment about the  $yz$ -plane is the integral

$$M_{yz} = \iiint_D x\delta(x, y, z) dV.$$

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For a two-dimensional object, such as a thin, flat plate, we calculate first moments about the coordinate axes by simply dropping the  $z$ -coordinate. So the first moment about the  $y$ -axis is the double integral over the region  $R$  forming the plate of the distance from the axis multiplied by the density, or

$$M_y = \iint_R x \delta(x, y) dA.$$

# Masses and First Moments

## Three-dimensional Solid

### THREE-DIMENSIONAL SOLID

**Mass:** Let  $\delta = \delta(x, y, z)$  be the density at  $(x, y, z)$

$$M = \iiint_D \delta \, dV$$

**First moments about the coordinate planes:**

$$M_{yz} = \iiint_D x \delta \, dV, \quad M_{xz} = \iiint_D y \delta \, dV, \quad M_{xy} = \iiint_D z \delta \, dV$$

**Center of mass:**

$$\bar{x} = \frac{M_{yz}}{M}, \quad \bar{y} = \frac{M_{xz}}{M}, \quad \bar{z} = \frac{M_{xy}}{M}$$

# Masses and First Moments

## Two-dimensional Plate

### TWO-DIMENSIONAL PLATE

**Mass:** Let  $\delta = \delta(x, y)$  be the density at  $(x, y)$

$$M = \iint_R \delta \, dA$$

**First moments:**

$$M_y = \iint_R x \delta \, dA, \quad M_x = \iint_R y \delta \, dA$$

**Center of mass:**

$$\bar{x} = \frac{M_y}{M}, \quad \bar{y} = \frac{M_x}{M}$$

# Masses and First Moments

## Example

### EXAMPLE

Find the center of mass of a solid of constant density  $\delta$  bounded below by the disk  $R : x^2 + y^2 \leq 4$  in the plane  $z = 0$  and above by the paraboloid  $z = 4 - x^2 - y^2$ .

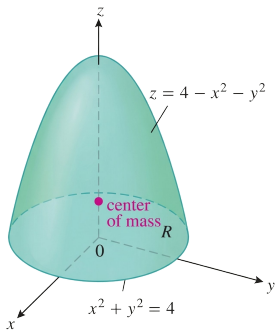
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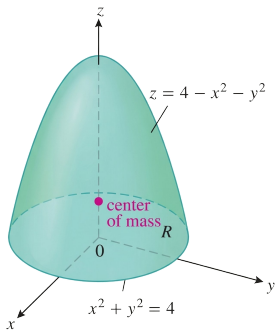
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### Solution:



By symmetry  $\bar{x} = \bar{y} = 0$ . To find  $\bar{z}$ ,

$$\begin{aligned} M_{xy} &= \iiint_R z \delta \, dz \, dy \, dx = \iint_R \left[ \frac{z^2}{2} \right]_{z=0}^{z=4-x^2-y^2} \delta \, dy \, dx \\ &= \frac{\delta}{2} \iint_R (4 - x^2 - y^2)^2 \, dy \, dx \\ &= \frac{\delta}{2} \int_0^{2\pi} \int_0^2 (4 - r^2)^2 r \, dr \, d\theta \\ &= \frac{\delta}{2} \int_0^{2\pi} \left[ -\frac{1}{6} (4 - r^2)^3 \right]_{r=0}^{r=2} d\theta \\ &= \frac{16\delta}{3} \int_0^{2\pi} d\theta = \frac{32\pi\delta}{3}. \end{aligned}$$

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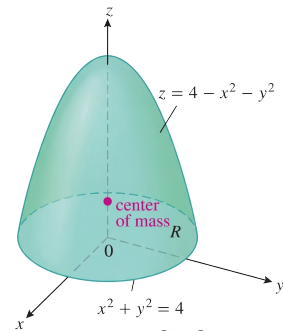
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$$M = \iiint_R \int_0^{4-x^2-y^2} \delta \, dz \, dy \, dx = 8\pi\delta \quad \rightarrow \quad \bar{z} = (M_{xy}/M) = 4/3, \quad (\bar{x}, \bar{y}, \bar{z}) = (0, 0, 4/3)$$

# Masses and First Moments

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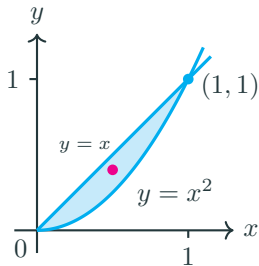
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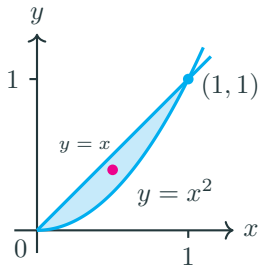
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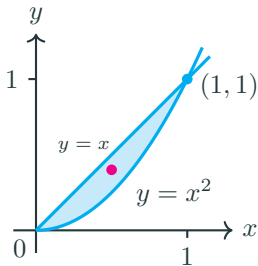
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$$\begin{aligned}M_x &= \int_0^1 \int_{x^2}^x y \, dy \, dx = \int_0^1 \left[ \frac{y^2}{2} \right]_{y=x^2}^{y=x} \, dx \\ &= \int_0^1 \left( \frac{x^2}{2} - \frac{x^4}{2} \right) \, dx = \int_0^1 \left( \frac{x^2 - x^4}{2} \right) \, dx \\ &= \left[ \frac{x^3}{6} - \frac{x^5}{10} \right]_0^1 = \frac{1}{6} - \frac{1}{10} = \frac{5 - 3}{30} = \frac{2}{30} = \frac{1}{15}\end{aligned}$$

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$$\bar{x} = \frac{M_y}{M} = \frac{1/12}{1/6} = \frac{1}{2}, \quad \bar{y} = \frac{M_x}{M} = \frac{1/15}{1/6} = \frac{2}{5}$$

# Masses and First Moments

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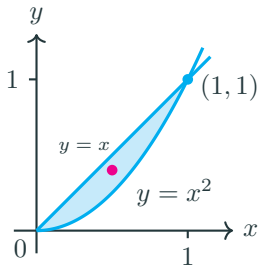
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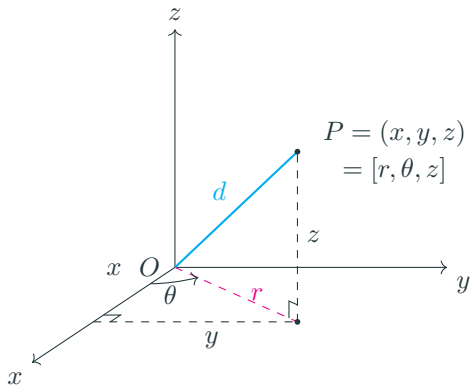


The centroid is the point  $(1/2, 2/5)$ .

# Change of Variables in Triple Integrals

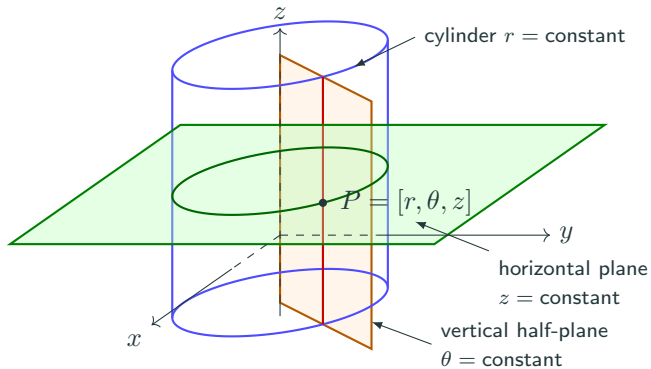
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# Integration in Cylindrical Coordinates



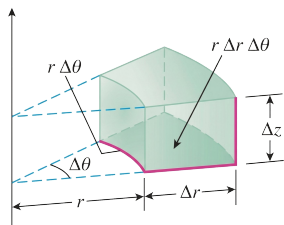
$$\begin{aligned}x &= r \cos \theta, & y &= r \sin \theta, & z &= z, \\r^2 &= x^2 + y^2, & \tan \theta &= \frac{y}{x}\end{aligned}$$

# Integration in Cylindrical Coordinates



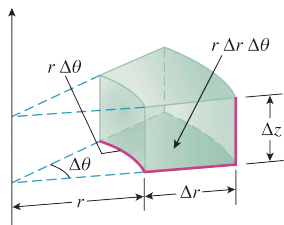
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When computing triple integrals over a region  $D$  in cylindrical coordinates, we partition the region into  $n$  small cylindrical wedges, rather than into rectangular boxes.



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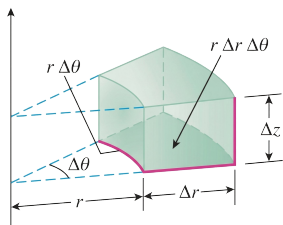


For a point  $(r_k, \theta_k, z_k)$  in the center of the  $k$ th wedge, we calculate in polar coordinates that  $\Delta A_k = r_k \Delta r_k \Delta\theta_k$ . So  $\Delta V_k = \Delta z_k r_k \Delta r_k \Delta\theta_k$  and a Riemann sum for  $f$  over  $D$  has the form

$$S_n = \sum_{k=1}^n f(r_k, \theta_k, z_k) \Delta z_k r_k \Delta r_k \Delta\theta_k.$$

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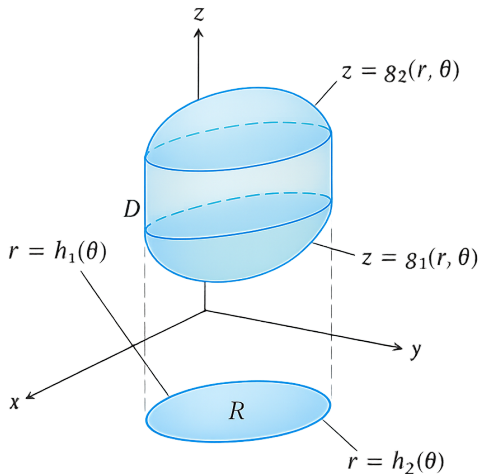
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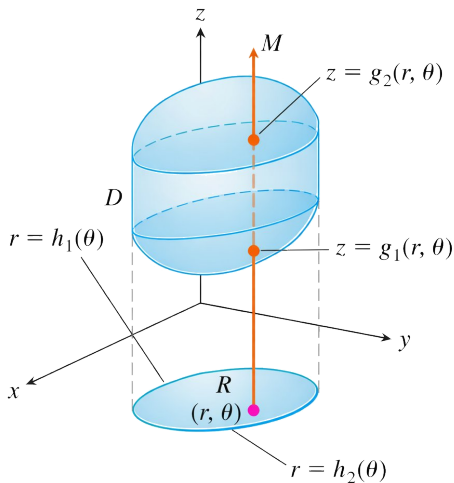
# How to Integrate in Cylindrical Coordinates

1. **Sketch:** Sketch the region  $D$  along with its projection  $R$  on the  $xy$ -plane. Label the surfaces and curves that bound  $D$  and  $R$ .



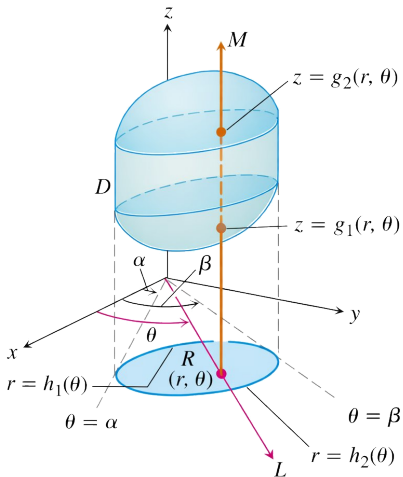
# How to Integrate in Cylindrical Coordinates

2. **Find the  $z$ -limits of integration:** Draw a line  $M$  through a typical point  $(r, \theta)$  of  $R$  parallel to the  $z$ -axis. As  $z$  increases,  $M$  enters  $D$  at  $z = g_1(r, \theta)$  and leaves at  $z = g_2(r, \theta)$ . These are the  $z$ -limits of integration.



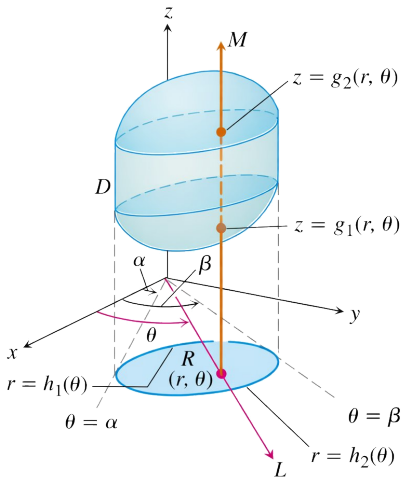
# How to Integrate in Cylindrical Coordinates

3. **Find the  $r$ -limits of integration:** Draw a ray  $L$  through  $(r, \theta)$  from the origin. The ray enters  $R$  at  $r = h_1(\theta)$  and leaves at  $r = h_2(\theta)$ . These are the  $r$ -limits of integration.



# How to Integrate in Cylindrical Coordinates

4. **Find the  $\theta$ -limits of integration:** As  $L$  sweeps across  $R$ , the angle  $\theta$  it makes with the positive  $x$ -axis runs from  $\theta = \alpha$  to  $\theta = \beta$ . These are the  $\theta$ -limits of integration.



# How to Integrate in Cylindrical Coordinates

5. **Writing triple integral:** Finally, construct the corresponding triple integral.

$$\begin{aligned} \iiint_D f(r, \theta, z) dV \\ = \int_{\theta=\alpha}^{\theta=\beta} \int_{r=h_1(\theta)}^{r=h_2(\theta)} \int_{z=g_1(r,\theta)}^{z=g_2(r,\theta)} f(r, \theta, z) dz r dr d\theta. \end{aligned}$$

# How to Integrate in Cylindrical Coordinates

## Example

### EXAMPLE

Find the centroid ( $\delta = 1$ ) of the solid enclosed by the cylinder  $x^2 + y^2 = 4$ , bounded above by the paraboloid  $z = x^2 + y^2$ , and bounded below by the  $xy$ -plane.

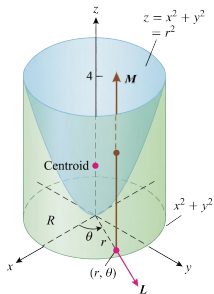
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The solid's centroid  $(\bar{x}, \bar{y}, \bar{z})$  lies on its axis of symmetry, here the  $z$ -axis. This makes  $\bar{x} = \bar{y} = 0$ . To find  $\bar{z}$ , we divide the first moment  $M_{xy}$  by the mass  $M$ .

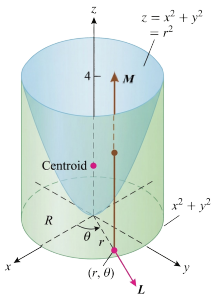
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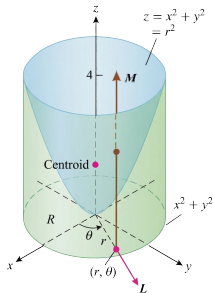
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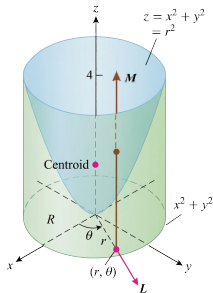
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$$\bar{z} = \frac{M_{xy}}{M} = \frac{32\pi}{3} \cdot \frac{1}{8\pi} = \frac{4}{3}$$

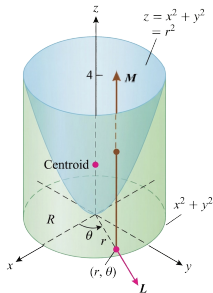
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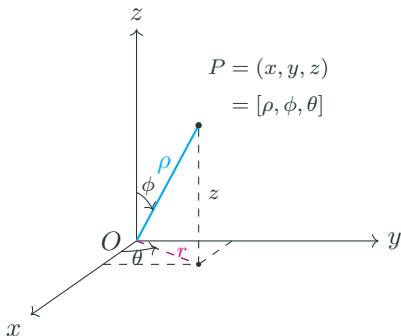


$$\begin{aligned} M &= \int_0^{2\pi} \int_0^2 \int_0^{r^2} dz r dr d\theta = \int_0^{2\pi} \int_0^2 [z]_0^{r^2} r dr d\theta \\ &= \int_0^{2\pi} \int_0^2 r^3 dr d\theta = \int_0^{2\pi} \left[ \frac{r^4}{4} \right]_0^2 d\theta = \int_0^{2\pi} 4 d\theta = 8\pi. \end{aligned}$$

$$\bar{z} = \frac{M_{xy}}{M} = \frac{32\pi}{3} \cdot \frac{1}{8\pi} = \frac{4}{3}$$

$$\text{Centroid} = \left(0, 0, \frac{4}{3}\right).$$

# Integration in Spherical Coordinates

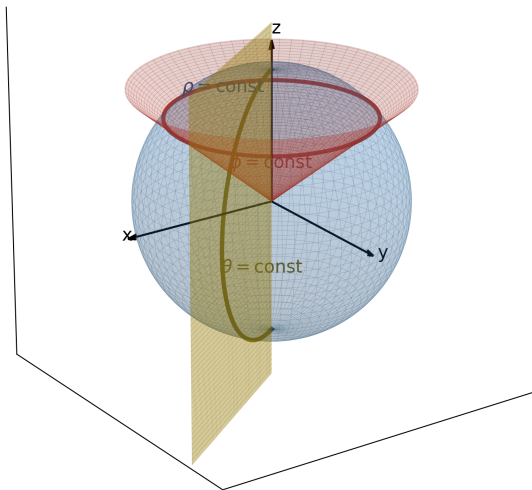


$$r = \rho \sin \phi, \quad x = r \cos \theta = \rho \sin \phi \cos \theta,$$

$$z = \rho \cos \phi, \quad y = r \sin \theta = \rho \sin \phi \sin \theta,$$

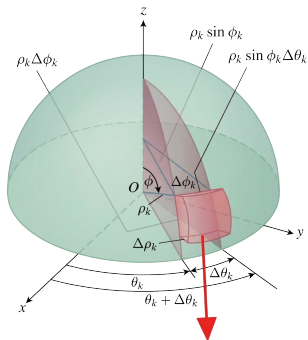
$$\rho = \sqrt{x^2 + y^2 + z^2} = \sqrt{r^2 + z^2}.$$

# Integration in Spherical Coordinates



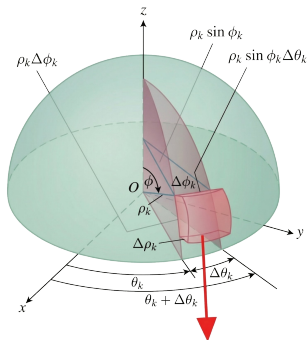
# Integration in Spherical Coordinates

When computing triple integrals over a region  $D$  in spherical coordinates, we partition the region into  $n$  spherical wedges.



$$\Delta V_k = \rho_k^2 \sin \phi_k \Delta\rho_k \Delta\phi_k \Delta\theta_k$$

# Integration in Spherical Coordinates

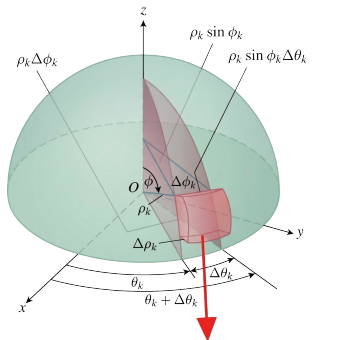


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$$S_n = \sum_{k=1}^n f(\rho_k, \phi_k, \theta_k) \rho_k^2 \sin \phi_k \Delta\rho_k \Delta\phi_k \Delta\theta_k.$$

# Integration in Spherical Coordinates



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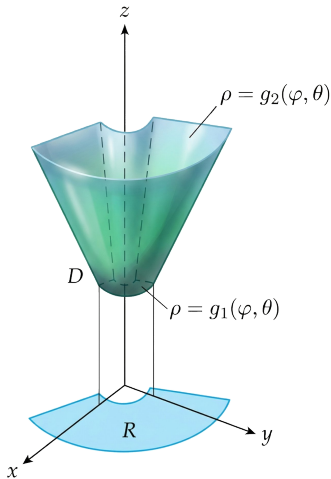
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$$\begin{aligned} \lim_{n \rightarrow \infty} S_n &= \iiint_D f(\rho, \phi, \theta) dV \\ &= \iiint_D f(\rho, \phi, \theta) \rho^2 \sin \phi d\rho d\phi d\theta. \end{aligned}$$

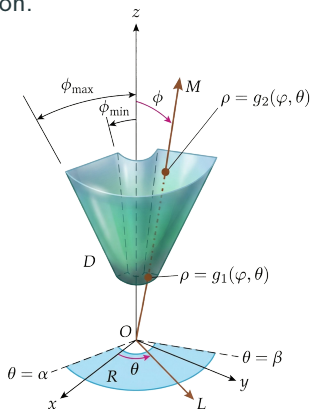
# How to Integrate in Spherical Coordinates

1. **Sketch:** Sketch the region  $D$  along with its projection  $R$  on the  $xy$ -plane. Label the surfaces that bound  $D$ .



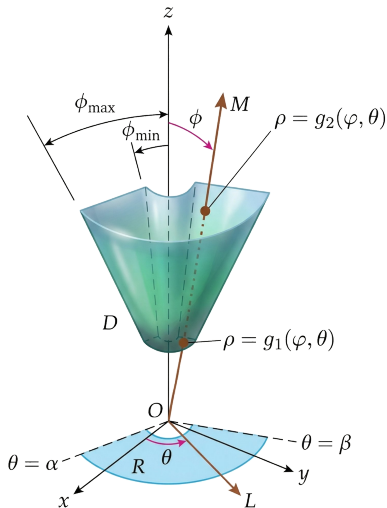
# How to Integrate in Spherical Coordinates

2. **Find the  $\rho$ -limits of integration:** Draw a ray  $M$  from the origin through  $D$  making an angle  $\phi$  with the positive  $z$ -axis. Also draw the projection of  $M$  on the  $xy$ -plane (call the projection  $L$ ). The ray  $L$  makes an angle  $\theta$  with the positive  $x$ -axis. As  $\rho$  increases,  $M$  enters  $D$  at  $\rho = g_1(\phi, \theta)$  and leaves at  $\rho = g_2(\phi, \theta)$ . These are the  $\rho$ -limits of integration.



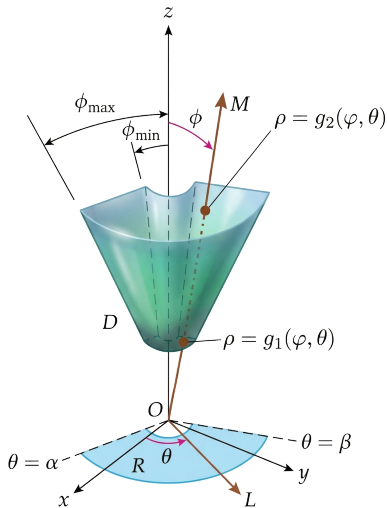
# How to Integrate in Spherical Coordinates

3. **Find the  $\phi$ -limits of integration:** For any given  $\theta$ , the angle  $\phi$  that  $M$  makes with the  $z$ -axis runs from  $\phi = \phi_{\min}$  to  $\phi = \phi_{\max}$ . These are the  $\phi$ -limits of integration.



# How to Integrate in Spherical Coordinates

4. **Find the  $\theta$ -limits of integration:** The ray  $L$  sweeps over  $R$  as  $\theta$  runs from  $\alpha$  to  $\beta$ . These are the  $\theta$ -limits of integration.



# How to Integrate in Spherical Coordinates

5. **Writing triple integral:** Finally, construct the corresponding triple integral.

$$\begin{aligned} & \iiint_D f(\rho, \phi, \theta) dV \\ &= \int_{\theta=\alpha}^{\theta=\beta} \int_{\phi=\phi_{\min}}^{\phi=\phi_{\max}} \int_{\rho=g_1(\phi,\theta)}^{\rho=g_2(\phi,\theta)} f(\rho, \phi, \theta) \rho^2 \sin \phi d\rho d\phi d\theta. \end{aligned}$$

# How to Integrate in Spherical Coordinates

## Example

### EXAMPLE

Find the volume of the “ice cream cone”  $D$  cut from the solid sphere

$\rho \leq 1$  by the cone  $\phi = \pi/3$ .

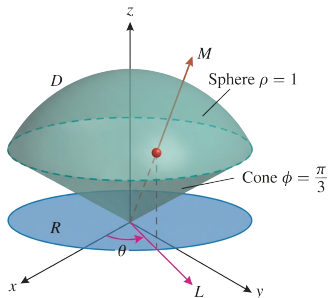
# How to Integrate in Spherical Coordinates

## Example

### EXAMPLE

Find the volume of the “ice cream cone”  $D$  cut from the solid sphere  $\rho \leq 1$  by the cone  $\phi = \pi/3$ .

### Solution:



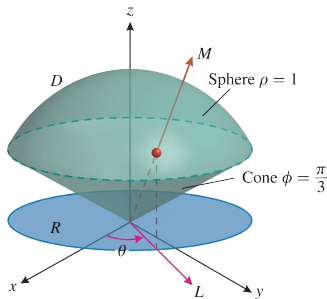
# How to Integrate in Spherical Coordinates

## Example

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Find the volume of the “ice cream cone”  $D$  cut from the solid sphere  $\rho \leq 1$  by the cone  $\phi = \pi/3$ .

### Solution:

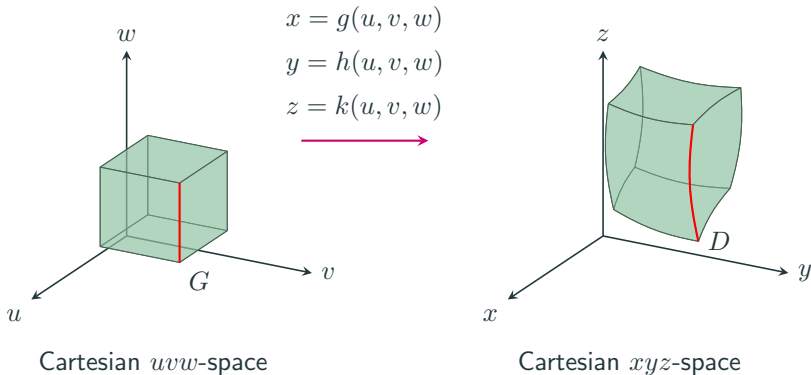


$$\begin{aligned} V &= \iiint_D \rho^2 \sin \phi \, d\rho \, d\phi \, d\theta \\ &= \int_0^{2\pi} \int_0^{\pi/3} \int_0^1 \rho^2 \sin \phi \, d\rho \, d\phi \, d\theta \\ &= \int_0^{2\pi} \int_0^{\pi/3} \left[ \frac{\rho^3}{3} \right]_0^1 \sin \phi \, d\phi \, d\theta \\ &= \int_0^{2\pi} \int_0^{\pi/3} \frac{1}{3} \sin \phi \, d\phi \, d\theta \\ &= \int_0^{2\pi} \left[ -\frac{1}{3} \cos \phi \right]_0^{\pi/3} d\theta \\ &= \int_0^{2\pi} \left( -\frac{1}{6} + \frac{1}{3} \right) d\theta = \frac{1}{6}(2\pi) = \frac{\pi}{3}. \end{aligned}$$

# Substitutions in Triple Integrals

Suppose that a region  $G$  in  $uvw$ -space is transformed one-to-one into the region  $D$  in  $xyz$ -space by differentiable equations of the form

$$x = g(u, v, w), \quad y = h(u, v, w), \quad z = k(u, v, w).$$



## Substitutions in Triple Integrals

Then any function  $F(x, y, z)$  defined on  $D$  can be thought of as a function

$$F(g(u, v, w), h(u, v, w), k(u, v, w)) = H(u, v, w)$$

defined on  $G$ . If  $g$ ,  $h$ , and  $k$  have continuous first partial derivatives, then the integral of  $F(x, y, z)$  over  $D$  is related to the integral of  $H(u, v, w)$  over  $G$  by the equation

$$\iiint_D F(x, y, z) \, dx \, dy \, dz = \iiint_G H(u, v, w) |J(u, v, w)| \, du \, dv \, dw,$$

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The factor  $J(u, v, w)$  is the **Jacobian determinant**

$$J(u, v, w) = \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} & \frac{\partial x}{\partial w} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} & \frac{\partial y}{\partial w} \\ \frac{\partial z}{\partial u} & \frac{\partial z}{\partial v} & \frac{\partial z}{\partial w} \end{vmatrix} = \frac{\partial(x, y, z)}{\partial(u, v, w)}.$$

# Substitutions in Triple Integrals

## Example

### EXAMPLE

Evaluate

$$\int_0^3 \int_0^4 \int_{x=y/2}^{x=(y/2)+1} \left( \frac{2x-y}{2} + \frac{z}{3} \right) dx dy dz$$

by applying the transformation  $u = (2x - y)/2$ ,  $v = y/2$ ,  $w = z/3$  and integrating over an appropriate region in  $uvw$ -space.

# Substitutions in Triple Integrals

## Example

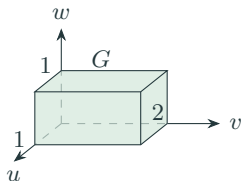
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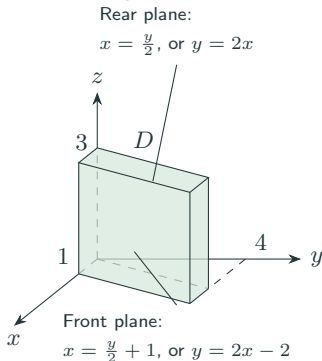
**Solution:**



$$x = u + v$$

$$y = 2v$$

$$z = 3w$$



# Substitutions in Triple Integrals

## Example

### EXAMPLE

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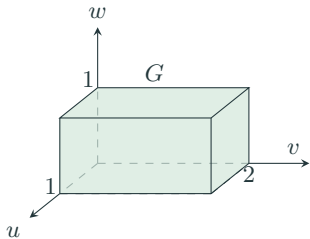
**Solution:** Since  $x = u + v$ ,  $y = 2v$ ,  $z = 3w$ , we have

$$J(u, v, w) = \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} & \frac{\partial x}{\partial w} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} & \frac{\partial y}{\partial w} \\ \frac{\partial z}{\partial u} & \frac{\partial z}{\partial v} & \frac{\partial z}{\partial w} \end{vmatrix} = \begin{vmatrix} 1 & 1 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 3 \end{vmatrix} = 6.$$

# Substitutions in Triple Integrals

## Example

**Solution:** Finally,



$$\begin{aligned} & \int_0^3 \int_0^4 \int_{x=y/2}^{x=(y/2)+1} \left( \frac{2x-y}{2} + \frac{z}{3} \right) dx dy dz \\ &= \int_0^1 \int_0^2 \int_0^1 (u+w) |J(u,v,w)| du dv dw \\ &= \int_0^1 \int_0^2 \int_0^1 (u+w)(6) du dv dw \\ &= 6 \int_0^1 \int_0^2 \left[ \frac{u^2}{2} + uw \right]_0^1 dv dw \\ &= 6 \int_0^1 \int_0^2 \left( \frac{1}{2} + w \right) dv dw \\ &= 6 \int_0^1 \left[ \frac{v}{2} + vw \right]_0^2 dw = 6 \int_0^1 (1 + 2w) dw = 12. \end{aligned}$$